

PELCO-P protocol

<i>Commands</i>	<i>Start byte</i>	<i>Motor unit No.</i>	<i>Command's code</i>		<i>Speeds (ignored)</i>		<i>Stop byte</i>	<i>Checksum</i>
LEFT	A0h	01h	00h	04h	3Fh	00h	AFh	35h
RIGHT	A0h	01h	00h	02h	3Fh	00h	AFh	33h
UP	A0h	01h	00h	08h	00h	3Fh	AFh	39h
DOWN	A0h	01h	00h	10h	00h	3Fh	AFh	21h
LEFT-UP	A0h	01h	00h	0Ch	3Fh	3Fh	AFh	02h
RIGHT-UP	A0h	01h	00h	0Ah	3Fh	3Fh	AFh	04h
RIGHT-DOWN	A0h	01h	00h	12h	3Fh	3Fh	AFh	1Ch
LEFT-DOWN	A0h	01h	00h	14h	3Fh	3Fh	AFh	1Ah
AUTO SCAN	A0h	01h	20h	00h	00h	00h	AFh	2Eh
STOP	A0h	01h	00h	00h	00h	00h	AFh	0Eh
ZOOM+	A0h	01h	00h	20h	00h	00h	AFh	2Eh
ZOOM-	A0h	01h	00h	40h	00h	00h	AFh	4Eh
FOCUS+	A0h	01h	01h	00h	00h	00h	AFh	0Fh
FOCUS-	A0h	01h	02h	00h	00h	00h	AFh	0Ch